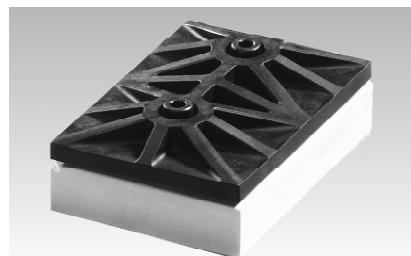


## SKiiP 30 NAB 12

Absolute Maximum Ratings		Values	Units
Symbol	Conditions <sup>1)</sup>		
Inverter	(Chopper see SKiiP 22 NAB 12)		
$V_{CES}$		1200	V
$V_{GES}$		$\pm 20$	V
$I_C$	$T_{heatsink} = 25 / 80^\circ\text{C}$	33 / 22	A
$I_{CM}$	$t_p < 1 \text{ ms}; T_{heatsink} = 25 / 80^\circ\text{C}$	66 / 44	A
$I_F = -I_C$	$T_{heatsink} = 25 / 80^\circ\text{C}$	38 / 26	A
$I_{FM} = -I_{CM}$	$t_p < 1 \text{ ms}; T_{heatsink} = 25 / 80^\circ\text{C}$	76 / 52	A
Bridge Rectifier			
$V_{RRM}$		1500	V
$I_D$	$T_{heatsink} = 80^\circ\text{C}$	35	A
$I_{FSM}$	$t_p = 10 \text{ ms}; \sin. 180^\circ, T_j = 25^\circ\text{C}$	700	A
$I^2t$	$t_p = 10 \text{ ms}; \sin. 180^\circ, T_j = 25^\circ\text{C}$	2400	$\text{A}^2\text{s}$
$T_j$		-40 ... +150	$^\circ\text{C}$
$T_{stg}$		-40 ... +125	$^\circ\text{C}$
$V_{isol}$	AC, 1 min.	2500	V

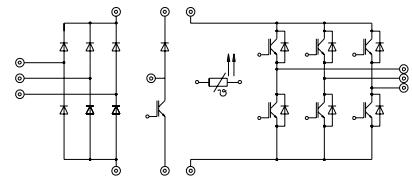
**MiniSKiiP 3**  
**SEMIKRON integrated intelligent Power**  
**SKiiP 30 NAB 12**  
**3-phase bridge rectifier + braking chopper + 3-phase bridge inverter**

Case M3



Characteristics		min.	typ.	max.	Units
Symbol	Conditions <sup>1)</sup>				
IGBT - Inverter					
$V_{CEsat}$	$I_C = 25 \text{ A}, T_j = 25 (125)^\circ\text{C}$	-	2,5(3,1)	3,0(3,7)	V
$t_{d(on)}$	$V_{CC} = 600 \text{ V}; V_{GE} = \pm 15 \text{ V}$	-	75	150	ns
$t_r$	$I_C = 25 \text{ A}; T_j = 125^\circ\text{C}$	-	65	130	ns
$t_{d(off)}$	$R_{gon} = R_{goff} = 47 \Omega$	-	400	600	ns
$t_f$	inductive load	-	50	100	ns
$E_{on} + E_{off}$		-	6,2	-	mJ
$C_{ies}$	$V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}, 1 \text{ MHz}$ per IGBT	-	1,65	-	nF
$R_{thjh}$		-	-	1,0	K/W
IGBT - Chopper *					
$V_{CEsat}$	$I_C = 15 \text{ A}, T_j = 25 (125)^\circ\text{C}$	-	2,5(3,1)	3,0(3,7)	V
$t_{d(on)}$	$V_{CC} = 600 \text{ V}; V_{GE} = \pm 15 \text{ V}$	-	55	110	ns
$t_r$	$I_C = 15 \text{ A}; T_j = 125^\circ\text{C}$	-	45	90	ns
$t_{d(off)}$	$R_{gon} = R_{goff} = 82 \Omega$	-	400	600	ns
$t_f$	inductive load	-	70	100	ns
$E_{on} + E_{off}$		-	4,0	-	mJ
$C_{ies}$	$V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}, 1 \text{ MHz}$ per IGBT	-	1,0	-	nF
$R_{thjh}$		-	-	1,4	K/W
Diode <sup>2)</sup> - Inverter (Diode <sup>2)</sup> - Chopper see SKiiP 22 NAB 12)					
$V_F = V_{EC}$	$I_F = 25 \text{ A}, T_j = 25 (125)^\circ\text{C}$	-	2,0(1,8)	2,5(2,3)	V
$V_{TO}$	$T_j = 125^\circ\text{C}$	-	1,0	1,2	V
$r_T$	$T_j = 125^\circ\text{C}$	-	32	44	$\text{m}\Omega$
$I_{RRM}$	$I_F = 25 \text{ A}, V_R = -600 \text{ V}$	-	25	-	A
$Q_{rr}$	$dI_F/dt = -500 \text{ A}/\mu\text{s}$	-	4,5	-	$\mu\text{C}$
$E_{off}$	$V_{GE} = 0 \text{ V}, T_j = 125^\circ\text{C}$	-	1,0	-	mJ
$R_{thjh}$	per diode	-	-	1,2	K/W
Diode - Rectifier					
$V_F$	$I_F = 35 \text{ A}, T_j = 25^\circ\text{C}$	-	1,2	-	V
$R_{thjh}$	per diode	-	-	1,6	K/W
Temperature Sensor					
$R_{TS}$	$T = 25 / 100^\circ\text{C}$	1000 / 1670			$\Omega$
Mechanical Data					
$M_1$	case to heatsink, SI Units	2	-	2,5	Nm
Case	mechanical outline see page B 16 – 9		M3		

\* For diagrams of the Chopper IGBT please refer to SKiiP 22 NAB 12



UL recognized file no. E63532

- specification of temperature sensor see part A
- common characteristics B 16 – 4

### Options

- also available with powerful chopper. For characteristics please refer to Inverter IGBT

1)  $T_{heatsink} = 25^\circ\text{C}$ , unless otherwise specified

2) CAL = Controlled Axial Lifetime Technology (soft and fast recovery)

MiniSKiiP 3

SKiiP 30 NAB 06  
SKiiP 31 NAB 06  
SKiiP 32 NAB 06  
SKiiP 30 NAB 12  
SKiiP 31 NAB 12  
SKiiP 32 NAB 12

## Circuit Case M3

### Layout and connections for the customer's printed circuit board

