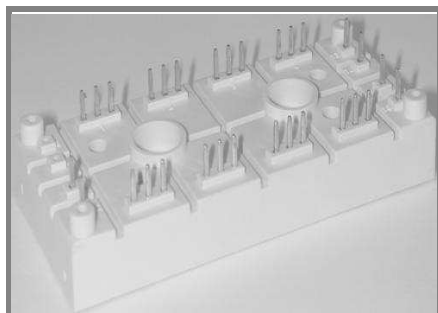


SKDH116/..L140



SEMIPONT™ 6

3-Phase Bridge Rectifier + IGBT braking chopper

SKDH116/..L140

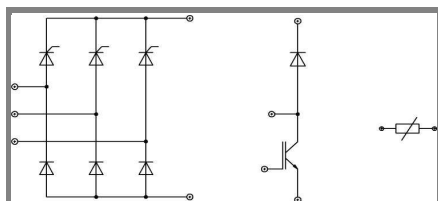
Data

Features

- Compact design
- Two screws mounting
- Heat transfer and isolation through direct copper bonded aluminium oxide ceramic (DCB)
- High surge currents
- Up to 1600V reverse voltage
- IGBT Trench4 inside; max $T_j=175^{\circ}\text{C}$
- CAL4F inside, max $T_j=175^{\circ}\text{C}$
- $I_{CM}/I_{FM} = 3 \times I_{C,nom}/I_{F,nom}$
- Rectifier diode, max $T_j=150^{\circ}\text{C}$

Typical Applications*

- DC drives
- Controlled filed rectifiers for DC motors
- Controlled battery charger



DH

V_{RSM} V	V_{RRM}, V_{DRM} V	$I_D = 110 \text{ A}$ (maximum value for continuous operation) ($T_s = 80^{\circ}\text{C}$)
1300	1200	SKDH116/12-L140
1700	1600	SKDH116/16-L140

Absolute Maximum Ratings		$T_s = 25^{\circ}\text{C}$, unless otherwise specified	
Symbol	Conditions	Values	Units
Bridge - Rectifier			
I_D	$T_s = 80^{\circ}\text{C}$; inductive load	110	A
I_{FSM}/I_{TSM}	$t_p = 10 \text{ ms}$; $\sin 180^{\circ}$; T_{jmax}	950	A
i^2t	$t_p = 10 \text{ ms}$; $\sin 180^{\circ}$; T_{jmax}	4500	A^2s
IGBT - Chopper			
V_{CES}/V_{GES}		1200 / 20	V
I_C	$T_s = 25 (70)^{\circ}\text{C}$	150 (120)	A
I_{CM}	$t_p = 1 \text{ ms}$; $T_s = 25 (70)^{\circ}\text{C}$	520	A
Freewheeling - CAL Diode			
V_{RRM}		1200	V
I_F	$T_s = 25 (70)^{\circ}\text{C}$	130 (105)	A
I_{FM}	$t_p = 1 \text{ ms}$; $T_s = 25 (70)^{\circ}\text{C}$	450	A
T_{vj}	Diode & IGBT (Thyristor)	- 40 ... + 175 (-40...+ 125)	$^{\circ}\text{C}$
T_{stg}		- 40 ... + 125	$^{\circ}\text{C}$
T_{solder}	terminals, 10 s	260	$^{\circ}\text{C}$
V_{isol}	a.c. (50) Hz, RMS 1 min. / 1 s	3000 / 3600	V

Characteristics		$T_s = 25^{\circ}\text{C}$, unless otherwise specified			
Symbol	Conditions	min.	typ.	max.	Units
Diode - Rectifier					
V_{TO} / r_t	$T_j = 125^{\circ}\text{C}$		0,8 / 7		V / mΩ
$R_{th(j-s)}$	per diode			1	K/W
Thyristor - Rectifier					
$V_{F(TO)} / r_t$	$T_j = 125^{\circ}\text{C}$		1,1 / 6		V / mΩ
$R_{th(j-s)}$	per Thyristor			0,85	K/W
I_{GD}	$T_j = 125^{\circ}\text{C}$; d.c.		5		mA
V_{GT} / I_{GT}	$T_j = 25^{\circ}\text{C}$			3 / 150	V / mA
I_H / I_L	$T_j = 25^{\circ}\text{C}$		250 / 600		mA
$(dv/dt)_{cr}$	$T_j = 125^{\circ}\text{C}$			1000	V/μs
$(di/dt)_{cr}$	$T_j = 125^{\circ}\text{C}$			100	A/μs
IGBT - Chopper					
$V_{CE(sat)}$	$I_C = 140 \text{ A}$, $T_j = 25^{\circ}\text{C}$; $V_{GE} = 15 \text{ V}$		1,85	2,1	V
$R_{th(j-s)}$	per IGBT		0,38		K/W
$t_{d(on)} / t_r$	valid for all values: $V_{CC} = 600 \text{ V}$; $V_{GE} = 15 \text{ V}$;		97 / 185		ns
$t_{d(off)} / t_f$	$I_C = 140 \text{ A}$; $T_j = 150^{\circ}\text{C}$;		443 / 82		ns
$E_{on} + E_{off}$	$T_j = 150^{\circ}\text{C}$; $R_G = 4 \Omega$; inductive load		63,3		mJ
CAL - Diode - Freewheeling					
$V_{T(TO)} / r_t$	$T_j = 150^{\circ}\text{C}$		0,9 / 7,8	1,1 / 8,6	V / mΩ
$R_{th(j-s)}$	per diode		0,56		K/W
I_{RRM}	valid for all values:		30		A
Q_{rr}	$I_F = 140 \text{ A}$; $V_R = - -600 \text{ V}$; $di_F/dt = - -1700 \text{ A}/\mu\text{s}$		9		μC
E_{off}	$V_{GE} = 0 \text{ V}$; $T_j = 150^{\circ}\text{C}$		7,92		mJ
Temperature Sensor					
R_{TS}	$T = 25 (100)^{\circ}\text{C}$;		1000 (1670)		Ω
Mechanical data					
M_S	mounting Torque		2,55	3,45	Nm

