

# IGBT Modules

## Sixpack

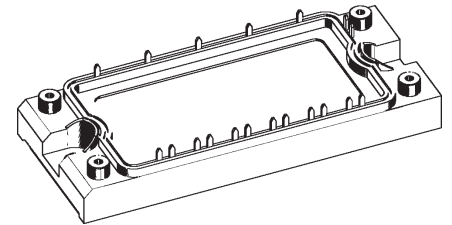
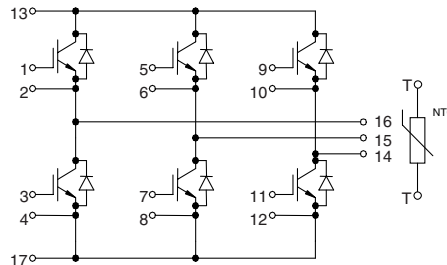
Short Circuit SOA Capability  
 Square RBSOA

$I_{C25} = 50 \text{ A}$   
 $V_{CES} = 1200 \text{ V}$   
 $V_{CE(sat) \text{ typ.}} = 2.2 \text{ V}$

Preliminary Data

**Type:** NTC - Option:

**MWI 25-12 A7** without NTC  
**MWI 25-12 A7T** with NTC



IGBTs			
Symbol	Conditions	Maximum Ratings	
$V_{CES}$	$T_{VJ} = 25^{\circ}\text{C to } 150^{\circ}\text{C}$	1200	V
$V_{GES}$		$\pm 20$	V
$I_{C25}$	$T_C = 25^{\circ}\text{C}$	50	A
$I_{C80}$	$T_C = 80^{\circ}\text{C}$	35	A
<b>RBSOA</b>	$V_{GE} = \pm 15 \text{ V}; R_G = 47 \Omega; T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 70$ $V_{CEK} \leq V_{CES}$	A
$t_{SC}$ <b>(SCSOA)</b>	$V_{CE} = V_{CES}; V_{GE} = \pm 15 \text{ V}; R_G = 47 \Omega; T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	$\mu\text{s}$
$P_{tot}$	$T_C = 25^{\circ}\text{C}$	225	W

### Features

- NPT IGBT technology
- low saturation voltage
- low switching losses
- switching frequency up to 30 kHz
- square RBSOA, no latch up
- high short circuit capability
- positive temperature coefficient for easy paralleling
- MOS input, voltage controlled
- ultra fast free wheeling diodes
- solderable pins for PCB mounting
- package with copper base plate

### Advantages

- space savings
- reduced protection circuits
- package designed for wave soldering

### Typical Applications

- AC motor control
- AC servo and robot drives
- power supplies

Symbol	Conditions	Characteristic Values ( $T_{VJ} = 25^{\circ}\text{C}$ , unless otherwise specified)			
		min.	typ.	max.	
$V_{CE(sat)}$	$I_C = 25 \text{ A}; V_{GE} = 15 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	2.2 2.6		V V	
$V_{GE(th)}$	$I_C = 1 \text{ mA}; V_{GE} = V_{CE}$	4.5		6.5 V	
$I_{CES}$	$V_{CE} = V_{CES}; V_{GE} = 0 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		2	2 mA mA	
$I_{GES}$	$V_{CE} = 0 \text{ V}; V_{GE} = \pm 20 \text{ V}$			200 nA	
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600 \text{ V}; I_C = 25 \text{ A}$ $V_{GE} = \pm 15 \text{ V}; R_G = 47 \Omega$		100 70 500 70	ns ns ns ns	
$E_{on}$			3.8	mJ	
$E_{off}$			2.8	mJ	
$C_{ies}$		$V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}; f = 1 \text{ MHz}$		1650	pF
$Q_{Gon}$		$V_{CE} = 600 \text{ V}; V_{GE} = 15 \text{ V}; I_C = 35 \text{ A}$		120	nC
$R_{thJC}$	(per IGBT)			0.55 K/W	

IXYS reserves the right to change limits, test conditions and dimensions.

**Diodes**

Symbol	Conditions	Maximum Ratings	
$I_{F25}$	$T_C = 25^\circ\text{C}$	50	A
$I_{F80}$	$T_C = 80^\circ\text{C}$	33	A

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 25\text{ A}; V_{GE} = 0\text{ V}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	2.3	2.7	V
$I_{RM}$ $t_{rr}$	$I_F = 25\text{ A}; di_F/dt = -400\text{ A}/\mu\text{s}; T_{VJ} = 125^\circ\text{C}$ $V_R = 600\text{ V}; V_{GE} = 0\text{ V}$	20		A
		200		ns
$R_{thJC}$	(per diode)			1.19 K/W

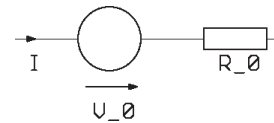
**Temperature Sensor NTC (MWI ... A7T version only)**

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{25}$ $B_{25/50}$	$T = 25^\circ\text{C}$	4.75	5.0	5.25 k $\Omega$
			3375	K

**Module**

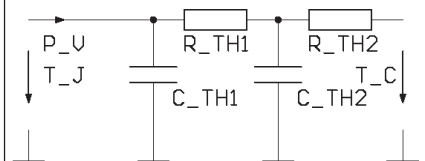
Symbol	Conditions	Maximum Ratings	
$T_{VJ}$ $T_{stg}$		-40...+150	$^\circ\text{C}$
		-40...+125	$^\circ\text{C}$
$V_{ISOL}$	$I_{ISOL} \leq 1\text{ mA}; 50/60\text{ Hz}$	2500	V~
$M_d$	Mounting torque (M5)	2.7 - 3.3	Nm

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{pin-chip}$			5	m $\Omega$
$d_S$ $d_A$	Creepage distance on surface Strike distance in air	6		mm
$R_{thCH}$	with heatsink compound		0.02	K/W
Weight			180	g

**Equivalent Circuits for Simulation**
**Conduction**


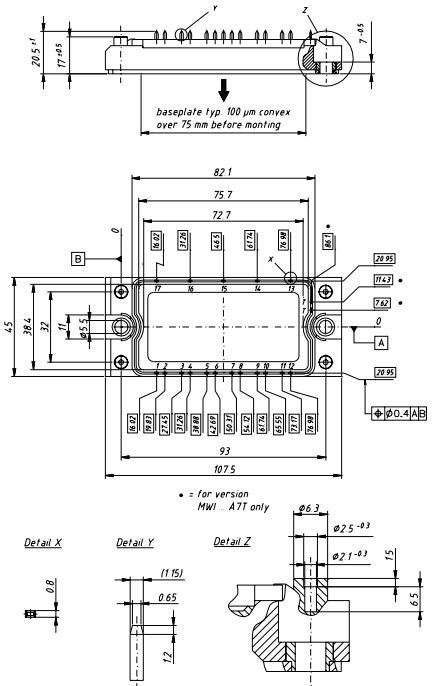
IGBT (typ. at  $V_{GE} = 15\text{ V}; T_J = 125^\circ\text{C}$ )  
 $V_0 = 1.5\text{ V}; R_0 = 40.7\text{ m}\Omega$

Free Wheeling Diode (typ. at  $T_J = 125^\circ\text{C}$ )  
 $V_0 = 1.3\text{ V}; R_0 = 16.0\text{ m}\Omega$

**Thermal Response**


IGBT (typ.)  
 $C_{th1} = 0.136\text{ J/K}; R_{th1} = 0.418\text{ K/W}$   
 $C_{th2} = 1.309\text{ J/K}; R_{th2} = 0.132\text{ K/W}$

Free Wheeling Diode (typ.)  
 $C_{th1} = 0.081\text{ J/K}; R_{th1} = 0.973\text{ K/W}$   
 $C_{th2} = 0.915\text{ J/K}; R_{th2} = 0.217\text{ K/W}$

**Dimensions in mm (1 mm = 0.0394")**


Higher magnification on page B3 - 72