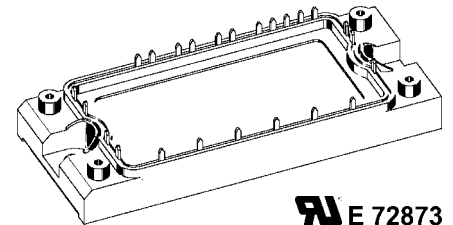
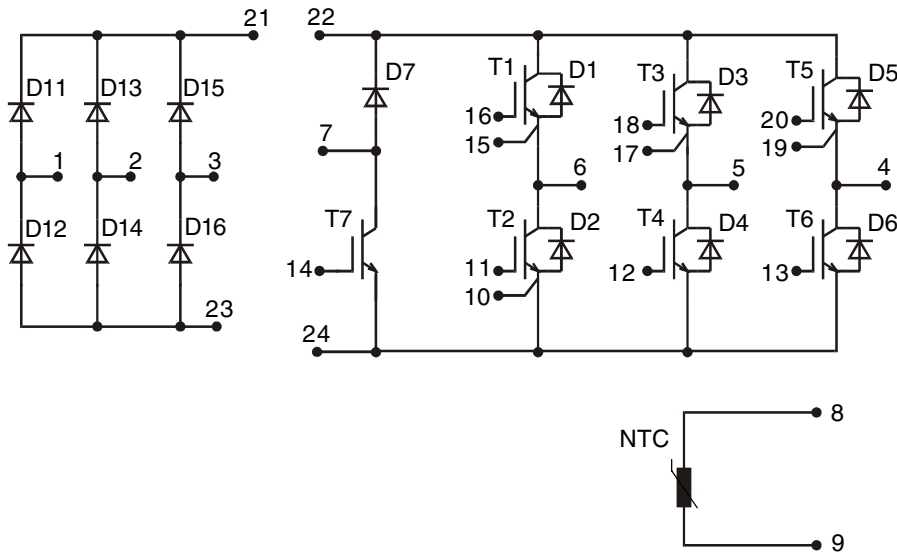


Converter - Brake - Inverter Module (CBI2)



E 72873

Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600V$	$V_{CES} = 600 V$	$V_{CES} = 600 V$
$I_{DAVM} = 36 A$	$I_{C25} = 26 A$	$I_{C25} = 50A$
$I_{FSM} = 300 A$	$V_{CE(sat)} = 1.9 V$	$V_{CE(sat)} = 1.9 V$

Input Rectifier Bridge D11 - D16

Symbol	Conditions	Maximum Ratings	
V_{RRM}		1600	V
I_{FAV}	$T_C = 80^\circ C$; sine 180°	25	A
I_{DAVM}	$T_C = 80^\circ C$; rectangular; $d = 1/3$	24	A
I_{FSM}	$T_{VJ} = 25^\circ C$; $t = 10 ms$; sine 50 Hz	300	A
P_{tot}	$T_C = 25^\circ C$	100	W

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^\circ C$, unless otherwise specified)		
		min.	typ.	max.
V_F	$I_F = 30 A$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		1.5 1.4	1.7 V V
I_R	$V_R = V_{RRM}$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		1.2	0.15 mA mA
t_{rr}	$V_R = 100 V$; $I_F = 15 A$; $di/dt = -15 A/\mu s$		1	μs
R_{thJC}	(per diode)			1.3 K/W

Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

Features

- High level of integration - only one power semiconductor module required for the whole drive
- Fast rectifier diodes for enhanced EMC behaviour
- NPT IGBT technology with low saturation voltage, low switching losses, high RBSOA and short circuit ruggedness
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

Output Inverter T1 - T6

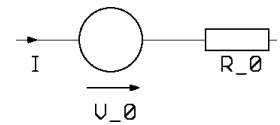
Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C}$ to 150°C	600	V
V_{GES}	Continuous	± 20	V
V_{GEM}	Transient	± 30	V
I_{C25}	$T_C = 25^{\circ}\text{C}$	50	A
I_{C80}	$T_C = 80^{\circ}\text{C}$	35	A
RBSOA	$V_{GE} = \pm 15\text{ V}$; $R_G = 33\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$	$I_{CM} = 60$ $V_{CEK} \leq V_{CES}$	A
t_{SC} (SCSOA)	$V_{CE} = V_{CES}$; $V_{GE} = \pm 15\text{ V}$; $R_G = 33\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	μs
P_{tot}	$T_C = 25^{\circ}\text{C}$	180	W

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified)			
		min.	typ.	max.	
$V_{CE(sat)}$	$I_C = 30\text{ A}$; $V_{GE} = 15\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	1.9 2.2	2.3	V V	
$V_{GE(th)}$	$I_C = 0.7\text{ mA}$; $V_{GE} = V_{CE}$	4.5	6.5	V	
I_{CES}	$V_{CE} = V_{CES}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	0.4	0.6	mA mA	
I_{GES}	$V_{CE} = 0\text{ V}$; $V_{GE} = \pm 20\text{ V}$		200	nA	
$t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off}	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 300\text{ V}$; $I_C = 30\text{ A}$ $V_{GE} = \pm 15\text{ V}$; $R_G = 33\ \Omega$		50 50 270 40	ns ns ns ns	
			1.4	1.0	mJ mJ
C_{ies}		$V_{CE} = 25\text{ V}$; $V_{GE} = 0\text{ V}$; $f = 1\text{ MHz}$	1600		pF
Q_{Gon}		$V_{CE} = 300\text{ V}$; $V_{GE} = 15\text{ V}$; $I_C = 30\text{ A}$	94		nC
R_{thJC}		(per IGBT)		0.7	K/W

Output Inverter D1 - D6

Symbol	Conditions	Maximum Ratings	
I_{F25}	$T_C = 25^{\circ}\text{C}$	72	A
I_{F80}	$T_C = 80^{\circ}\text{C}$	45	A

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
V_F	$I_F = 30\text{ A}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		1.2	1.6 V V
I_{RM} t_{rr}	$I_F = 30\text{ A}$; $di_F/dt = -500\text{ A}/\mu\text{s}$; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 300\text{ V}$; $V_{GE} = 0\text{ V}$		25	A ns
			90	
R_{thJC}	(per diode)		1.19	K/W

Equivalent Circuits for Simulation
Conduction

D11 - D16

Rectifier Diode (typ. at $T_J = 125^{\circ}\text{C}$)
 $V_0 = 1.19\text{ V}$; $R_0 = 9\text{ m}\Omega$

T1 - T6 / D1 - D6

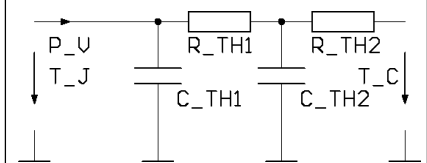
IGBT (typ. at $V_{GE} = 15\text{ V}$; $T_J = 125^{\circ}\text{C}$)
 $V_0 = 0.95\text{ V}$; $R_0 = 42\text{ m}\Omega$

Free Wheeling Diode (typ. at $T_J = 125^{\circ}\text{C}$)
 $V_0 = 0.89\text{ V}$; $R_0 = 8\text{ m}\Omega$

T7 / D7

IGBT (typ. at $V_{GE} = 15\text{ V}$; $T_J = 125^{\circ}\text{C}$)
 $V_0 = 0.99\text{ V}$; $R_0 = 81\text{ m}\Omega$

Free Wheeling Diode (typ. at $T_J = 125^{\circ}\text{C}$)
 $V_0 = 1.07\text{ V}$; $R_0 = 23\text{ m}\Omega$

Thermal Response

D11 - D16

Rectifier Diode (typ.)
 $C_{th1} = 0.106\text{ J/K}$; $R_{th1} = 1.06\text{ K/W}$
 $C_{th2} = 0.79\text{ J/K}$; $R_{th2} = 0.239\text{ K/W}$

T1 - T6 / D1 - D6

IGBT (typ.)
 $C_{th1} = 0.156\text{ J/K}$; $R_{th1} = 0.545\text{ K/W}$
 $C_{th2} = 1.164\text{ J/K}$; $R_{th2} = 0.155\text{ K/W}$

Free Wheeling Diode (typ.)
 $C_{th1} = 0.116\text{ J/K}$; $R_{th1} = 0.973\text{ K/W}$
 $C_{th2} = 0.88\text{ J/K}$; $R_{th2} = 0.217\text{ K/W}$

T7 / D7

IGBT (typ.)
 $C_{th1} = 0.077\text{ J/K}$; $R_{th1} = 1.111\text{ K/W}$
 $C_{th2} = 0.732\text{ J/K}$; $R_{th2} = 0.279\text{ K/W}$

Free Wheeling Diode (typ.)
 $C_{th1} = 0.043\text{ J/K}$; $R_{th1} = 2.738\text{ K/W}$
 $C_{th2} = 0.54\text{ J/K}$; $R_{th2} = 0.462\text{ K/W}$

Brake Chopper T7

Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C}$ to 150°C	600	V
V_{GES}	Continuous	± 20	V
V_{GEM}	Transient	± 30	V
I_{C25}	$T_C = 25^{\circ}\text{C}$	26	A
I_{C80}	$T_C = 80^{\circ}\text{C}$	19	A
RBSOA	$V_{GE} = \pm 15\text{ V}$; $R_G = 68\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$	$I_{CM} = 30$ $V_{CEK} \leq V_{CES}$	A
t_{SC} (SCSOA)	$V_{CE} = V_{CES}$; $V_{GE} = \pm 15\text{ V}$; $R_G = 68\ \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	μs
P_{tot}	$T_C = 25^{\circ}\text{C}$	95	W

Symbol	Conditions	Characteristic Values			
		$(T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified)			
		min.	typ.	max.	
$V_{CE(sat)}$	$I_C = 15\text{ A}$; $V_{GE} = 15\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		1.9 2.1	2.3 V V	
$V_{GE(th)}$	$I_C = 0.4\text{ mA}$; $V_{GE} = V_{CE}$	4.5		6.5 V	
I_{CES}	$V_{CE} = V_{CES}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		0.3	0.5 mA mA	
I_{GES}	$V_{CE} = 0\text{ V}$; $V_{GE} = \pm 20\text{ V}$			200 nA	
$t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off}	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 300\text{ V}$; $I_C = 15\text{ A}$ $V_{GE} = \pm 15\text{ V}$; $R_G = 68\ \Omega$		30 50 270 40	ns ns ns ns	
				0.7 0.5	mJ mJ
C_{ies}		$V_{CE} = 25\text{ V}$; $V_{GE} = 0\text{ V}$; $f = 1\text{ MHz}$		800	pF
Q_{Gon}		$V_{CE} = 300\text{ V}$; $V_{GE} = 15\text{ V}$; $I_C = 15\text{ A}$		57	nC
R_{thJC}					1.3 K/W

Brake Chopper D7

Symbol	Conditions	Maximum Ratings	
V_{RRM}	$T_{VJ} = 25^{\circ}\text{C}$ to 150°C	600	V
I_{F25}	$T_C = 25^{\circ}\text{C}$	22	A
I_{F80}	$T_C = 80^{\circ}\text{C}$	15	A

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
V_F	$I_F = 15\text{ A}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		1.5	2.2 V V
I_R	$V_R = V_{RRM}$; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$		0.07	0.06 mA mA
I_{RM} t_{rr}	$I_F = 10\text{ A}$; $di_F/dt = -400\text{ A}/\mu\text{s}$; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 300\text{ V}$		11 80	A ns
R_{thJC}				3.2 K/W

Temperature Sensor NTC

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
R_{25}	$T = 25^{\circ}\text{C}$	4.75	5.0	5.25 k Ω
$B_{25/50}$			3375	K

Module

Symbol	Conditions	Maximum Ratings	
T_{VJ}	Operating	-40...+125	$^{\circ}\text{C}$
T_{JM}		150	$^{\circ}\text{C}$
T_{stg}		-40...+125	$^{\circ}\text{C}$
V_{ISOL}	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~
M_d	Mounting torque (M5)	2.7 - 3.3	Nm

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{pin-chip}$			5	m Ω
d_s	Creepage distance on surface	6		mm
d_A	Strike distance in air	6		mm
R_{thCH}	with heatsink compound		0.02	K/W
Weight			180	g

Dimensions in mm (1 mm = 0.0394")

